



# Improving few shot object classification using contrastive learning

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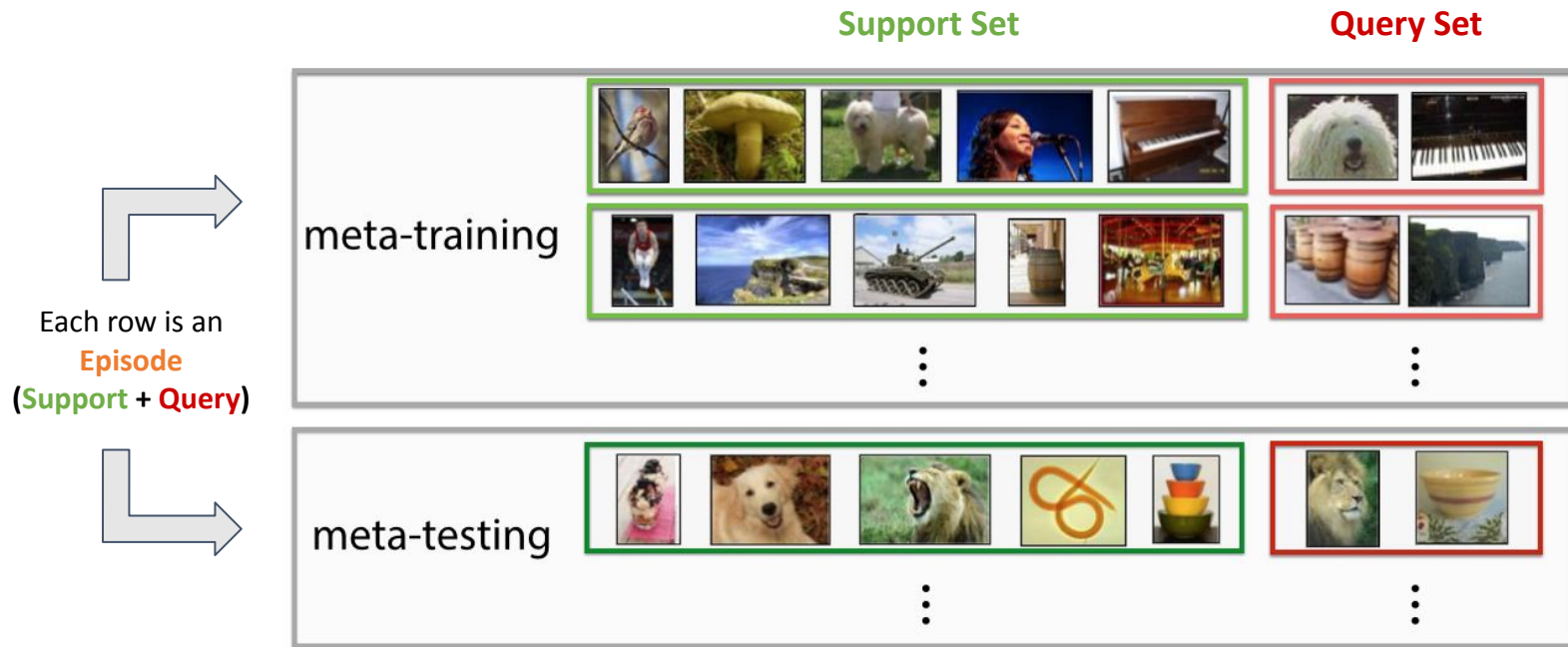
CS 6301.004 - Deep Learning For NLP

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# Improving **few shot** object classification using contrastive learning

- Few-Shot Learning is a sub-area of machine learning. It's about classifying **new data** when you have only a **few training samples** with **supervised information** ([neptune.ai](https://neptune.ai)).
- Formulated as an N-way-K-shot problem (**Episodes**)
  - N := number of classes
  - K := number of samples per class
    - In a fixed setup, this remains same for all classes
    - In a variable setup, this varies across classes

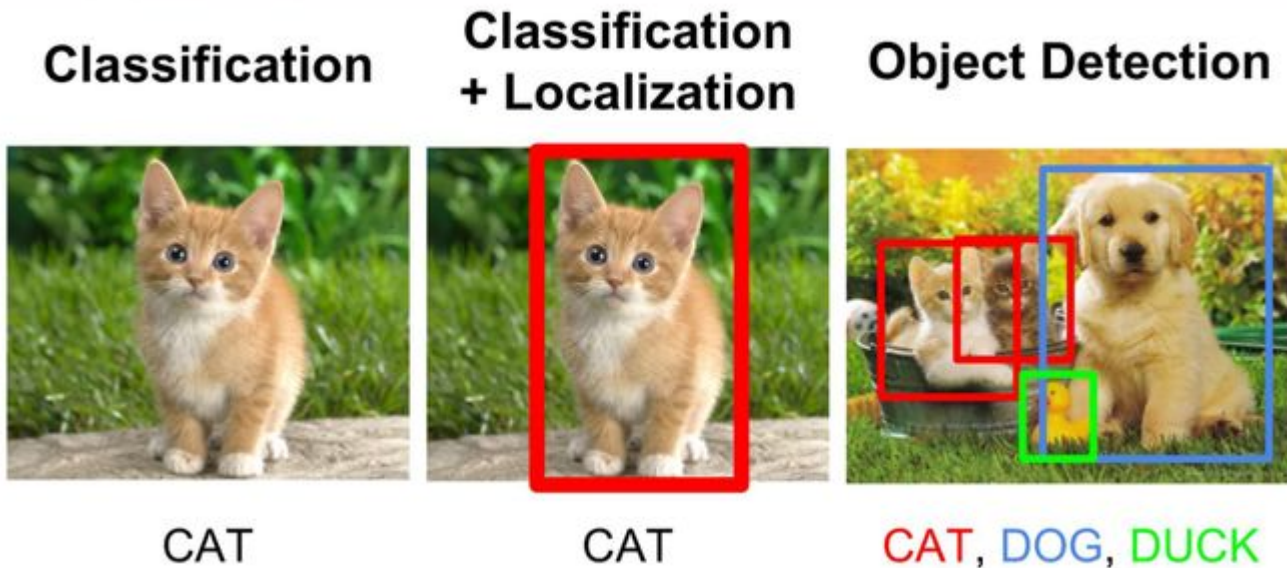
# Improving **few shot** object classification using contrastive learning



Here, it's a **5-way-1-shot** setup (**fixed** episode variant)

Image: <https://bair.berkeley.edu/blog/2017/07/18/learning-to-learn>

# Improving few shot **object classification** using contrastive learning

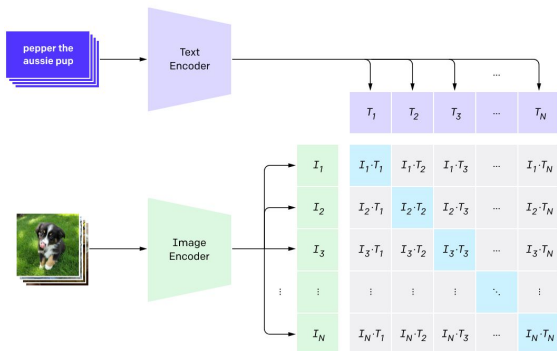


We will be dealing with **classification** only. i.e. Given an image containing a single object, classify it.

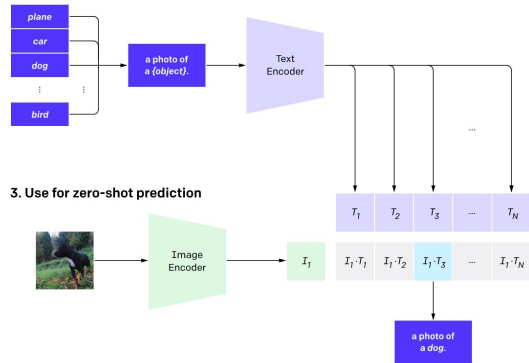
Image: <https://www.kaggle.com/getting-started/169984>

# Related Works

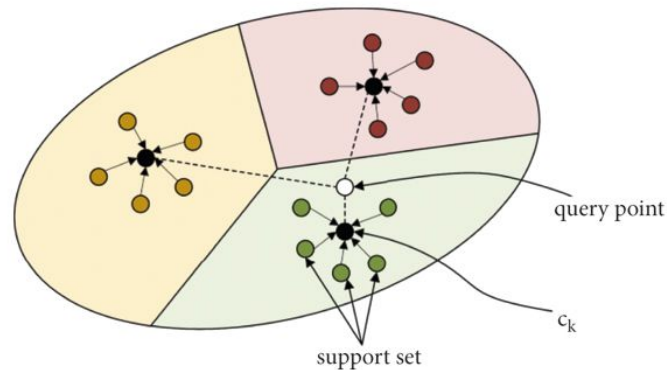
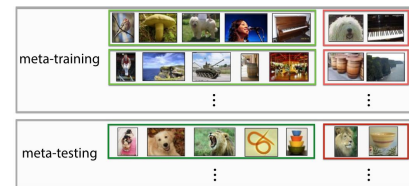
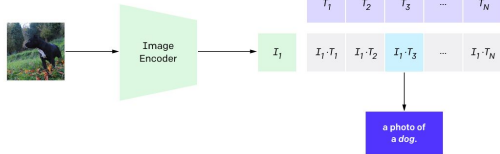
## 1. Contrastive pre-training



## 2. Create dataset classifier from label text



## 3. Use for zero-shot prediction



$$c_k = \frac{1}{|S_k|} \sum_{(x_i, y_i) \in S_k} f_\phi(x_i)$$

$$p_\phi(y = k | x) = \frac{\exp(-d(f_\phi(x), c_k))}{\sum_{k'} \exp(-d(f_\phi(x), c_{k'}))}$$

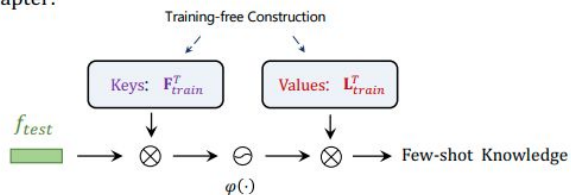
$$\min J(\phi) = -\log p_\phi(y = k | x)$$

Snell, Jake, Kevin Swersky, and Richard Zemel. "Prototypical networks for few-shot learning." NeurIPS 2017.

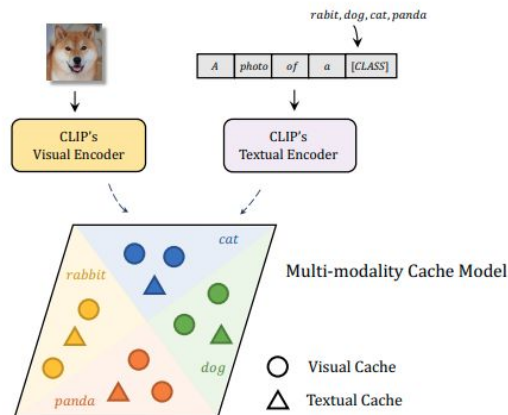
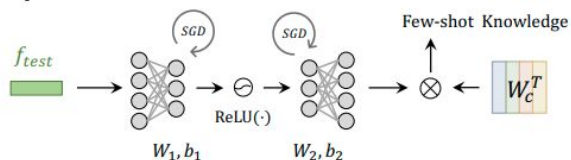
# Related Vs Ours

Method	Use Support Sets	Adapt Image Encoder	Adapt Text Encoder	Align Image and Text
Zero-shot CLIP [18]	✗	✗	✗	✓
Linear-probe CLIP [18]	✓	✗	✗	✗
CoOp [26]	✓	✗	✓	✗
CLIP-Adapter [8]	✓	✓	✗	✗
Tip-Adapter [25]	✓	✓	✗	✗
<b>Proposed Method</b>	✓	✓	✓	✓

Tip-Adapter:

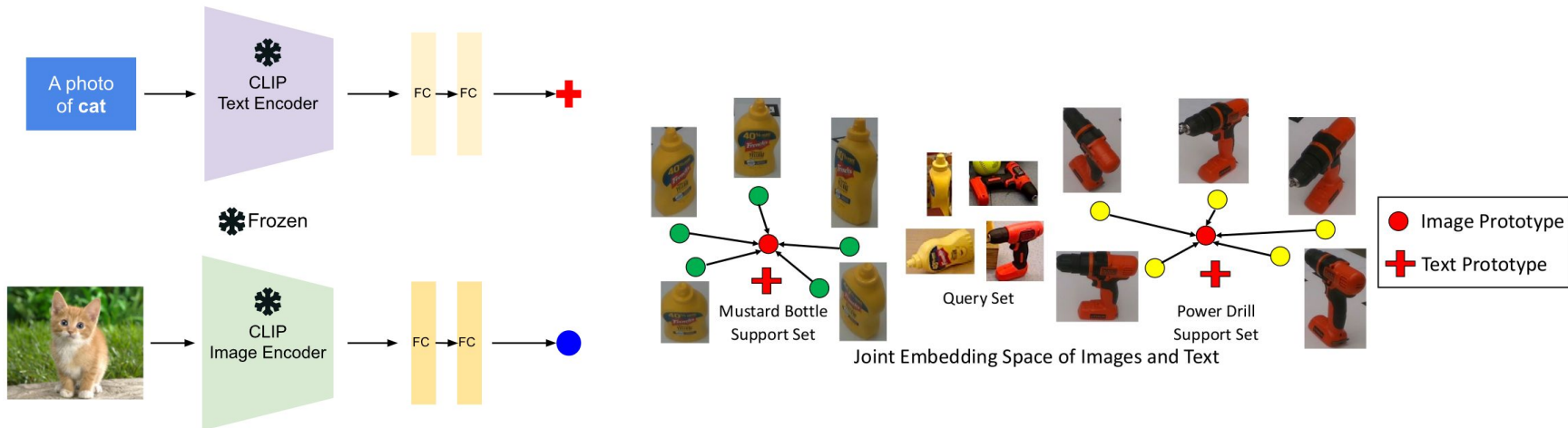


CLIP-Adapter:



# Proposed Method

## Proto-CLIP (Model#1)



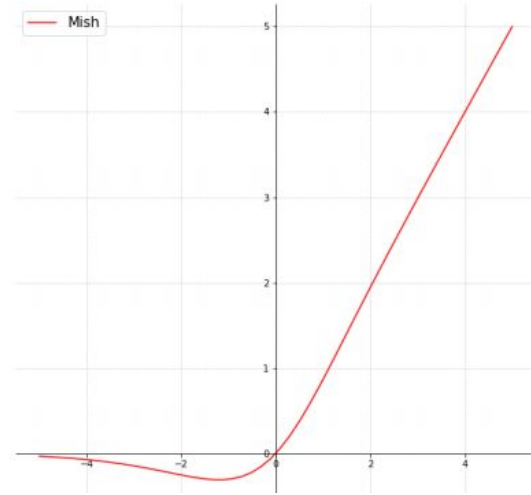
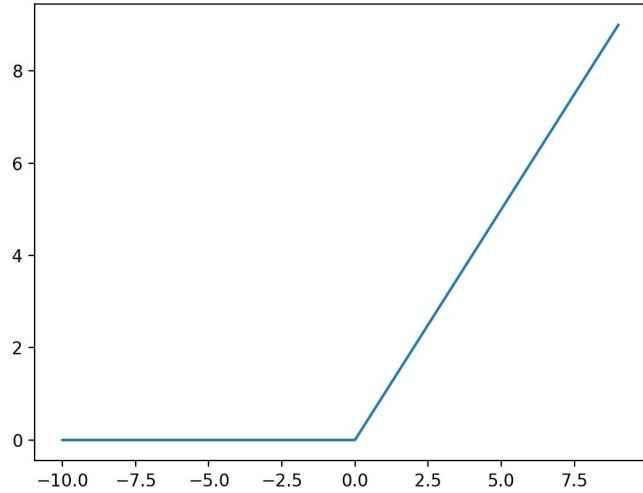
$$P(y = k | \mathbf{x}^q, \mathcal{S}) = \alpha P(y = k | \mathbf{x}^q, \mathcal{S}_x) + (1 - \alpha) P(y = k | \mathbf{x}^q, \mathcal{S}_y)$$

Loss: Negative Log Likelihood

Our proposed **Proto-CLIP** model learns a *joint embedding space of images and text*, where *image prototypes* and *text prototypes* are learned using *support sets* for few-shot classification.

**Metric:** Accuracy

# Activation Fn.: ReLU vs Mish



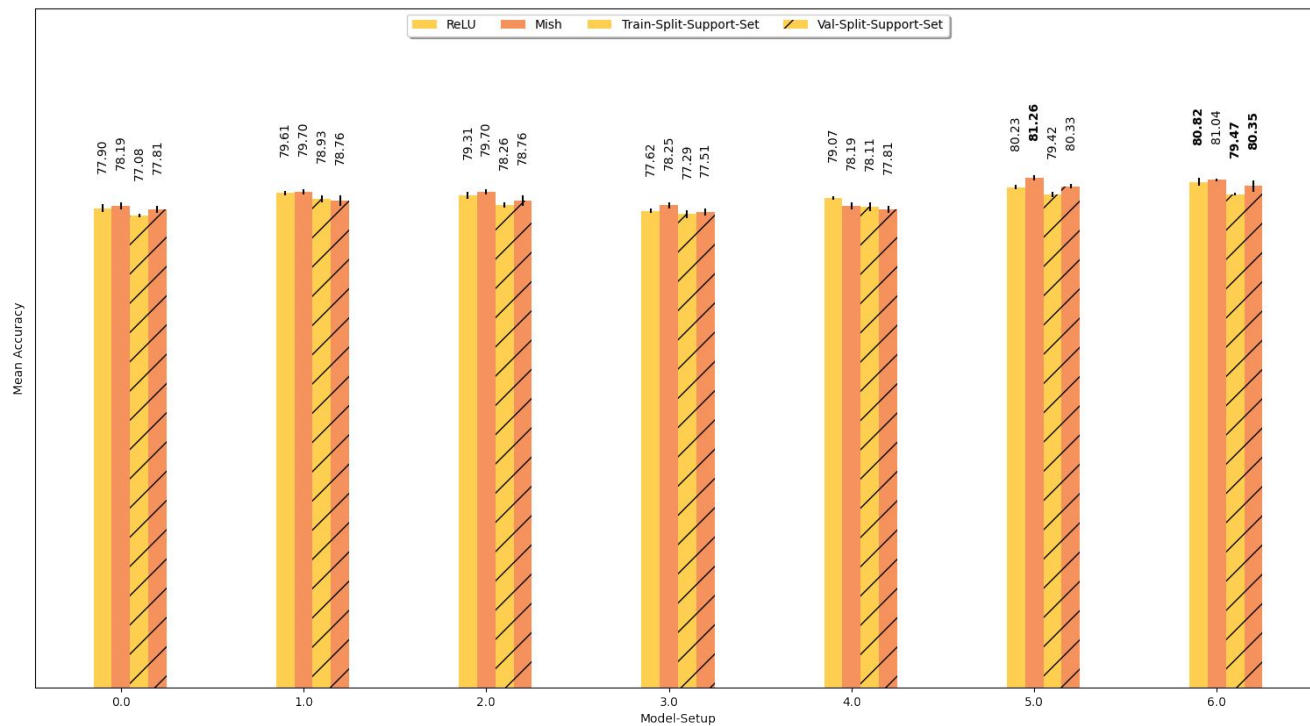
Source: <https://krutikapat.github.io/Swish-Vs-Mish-Latest-Activation-Functions/>



# Model#1 Variants

Model-Setup	Res	Tau	CosineAnneal	Output_Embedding_Size		{Input,hidden,output} sizes	
						ViT-B/32	ViT-L/14
0	0	0	0	Config_Output_Size		512, 256, 128	768, 512, 256
1	1	0	0	Config_Input_Size		512, 512, 512	768, 768, 768
2	1	1	0	Config_Input_Size		512, 512, 512	768, 768, 768
3	0	1	0	Config_Input_Size		512, 512, 512	768, 768, 768
4	0	1	0	Config_Output_Size		512, 256, 128	768, 512, 256
5	0	1	1	Config_Output_Size		512, 256, 128	768, 512, 256
6	1	1	1	Config_Input_Size		512, 512, 512	768, 768, 768
						CosineAnneal	
						0	Adam Opt
						1	AdamW Opt + CosineAnnealing (eps=1e-4 same as Tip-A)
						Tau	
						0	1
						1	sqrt(output_embedding_size)

# Backbone: ViT-L/14 | ReLU vs Mish

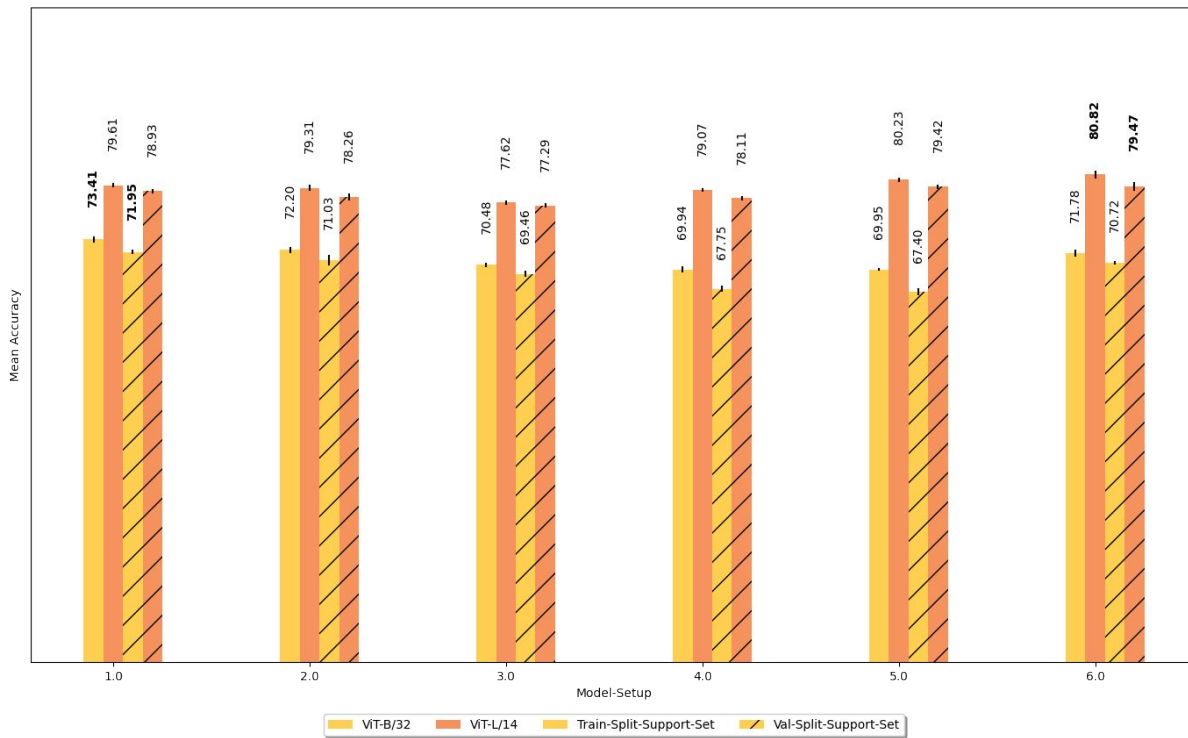


# Sample t-SNE plot for Model#1

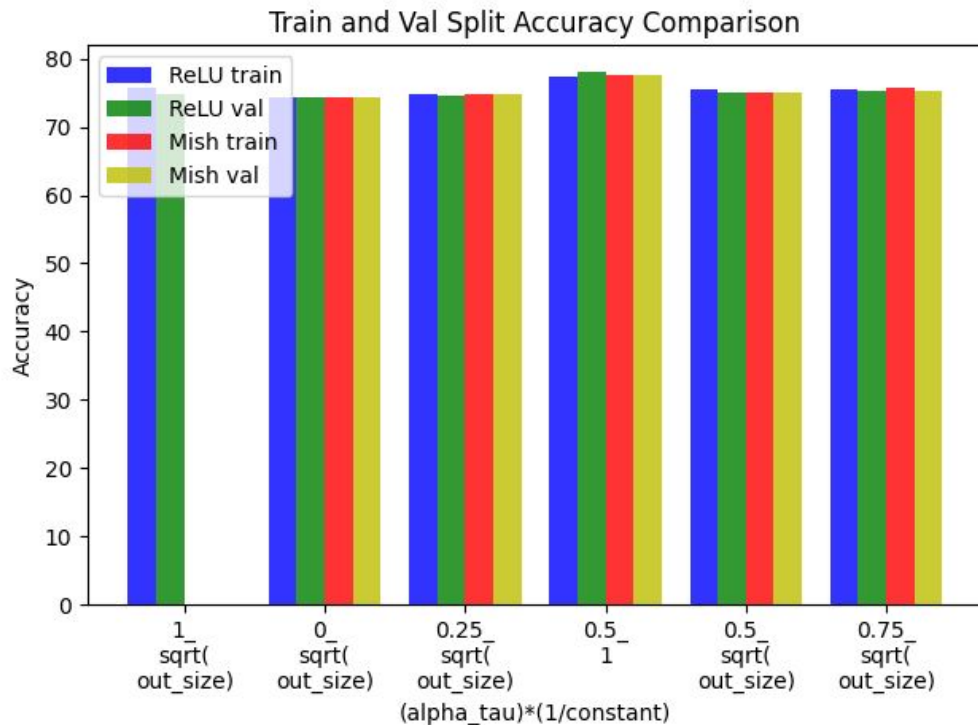


(Setup#1)

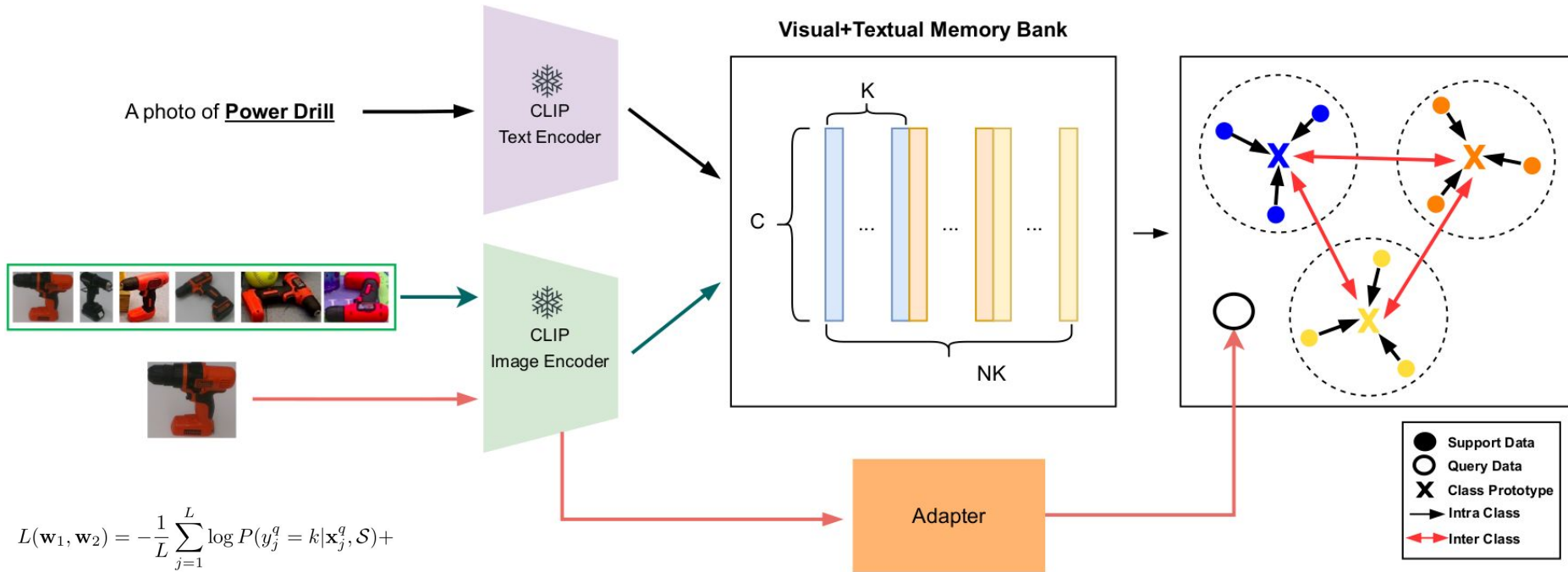
# ReLU: ViT-B/32 vs ViT-L/14



# DTD Results (Model-Setup#6)



# Proposed Method: Proto-CLIP (V2)



$$L(\mathbf{w}_1, \mathbf{w}_2) = -\frac{1}{L} \sum_{j=1}^L \log P(y_j^q = k | \mathbf{x}_j^q, \mathcal{S}) +$$

$$\frac{1}{N} \sum_{k=1}^N (L_2^k(\mathbf{c}_k^x, \{\mathbf{c}_{k'}^y\}_{k'=1}^N) + L_3^k(\mathbf{c}_k^y, \{\mathbf{c}_{k'}^x\}_{k'=1}^N))$$

**alpha**

$$P(y = k | \mathbf{x}^q, \mathcal{S}) = \alpha P_i + (1 - \alpha) P_t \quad (1)$$

$$P_i = P(y = k | \mathbf{x}^q, \mathcal{S}_x), P_t = P(y = k | \mathbf{x}^q, \mathcal{S}_y)$$

**Beta (temperature)**

$$P(y = k | \mathbf{x}^q, \mathcal{S}_x) = \frac{\exp(-\|g_{\mathbf{w}_1}(\mathbf{x}^q) - \mathbf{c}_k^x\|_2^2)}{\sum_{k'=1}^N \exp(-\|g_{\mathbf{w}_1}(\mathbf{x}^q) - \mathbf{c}_{k'}^x\|_2^2)} \quad (2)$$

$$P(y = k | \mathbf{x}^q, \mathcal{S}_y) = \frac{\exp(-\|g_{\mathbf{w}_1}(\mathbf{x}^q) - \mathbf{c}_k^y\|_2^2)}{\sum_{k'=1}^N \exp(-\|g_{\mathbf{w}_1}(\mathbf{x}^q) - \mathbf{c}_{k'}^y\|_2^2)}$$

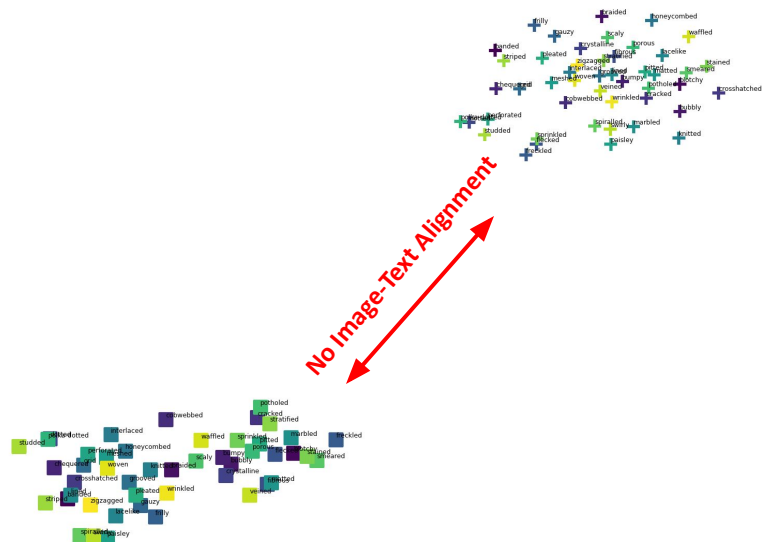
$$L_2^k(\mathbf{c}_k^x, \{\mathbf{c}_{k'}^y\}_{k'=1}^N) = -\log \frac{\exp(\mathbf{c}_k^x \cdot \mathbf{c}_k^y)}{\sum_{k'=1}^N \exp(\mathbf{c}_k^x \cdot \mathbf{c}_{k'}^y)} \quad (3)$$

$$L_3^k(\mathbf{c}_k^y, \{\mathbf{c}_{k'}^x\}_{k'=1}^N) = -\log \frac{\exp(\mathbf{c}_k^y \cdot \mathbf{c}_k^x)}{\sum_{k'=1}^N \exp(\mathbf{c}_k^y \cdot \mathbf{c}_{k'}^x)}$$

# Config + Loss Ablation Study

```
# ----- root_path/dataset_name -----  
root_path: 'DATA'  
  
# ----- Basic Config -----  
shots: 16  
backbone: 'RN50'  
  
lr: 0.0001  
augment_epoch: 10  
train_epoch: 100  
delta: .5  
  
# loss comments based on stanford_cars dataset  
losses: ['L1', 'L2', 'L3'] # better than L1, L2, L3, L4  
  
# losses: ['L1', 'L3', 'L4'] # just below L1, L2, L3  
  
# losses: ['L1', 'L2'] # on par with L1+L2+L3  
# losses: ['L1', 'L3'] # on par with L1+L2+L3  
  
# losses: ['L1'] # overfits; test accuracy near 0  
# losses: ['L2'] # not very effective, test accuracy just below few pc w.r.t. zero-shot  
# losses: ['L3'] # helps more than L2 alone. not very effective, test accuracy just below few pc w.r.t. zero-shot  
# losses: ['L4'] # doesn't help; decreases learning performance  
  
# losses: ['L2', 'L3'] # helps more than L2, L3 alone. Not very effective, test accuracy just below few pc w.r.t. zero-shot  
  
# losses: ['L2', 'L3', 'L4'] # doesn't help; worsens the training
```

# t-SNE visualisation



Alpha: 0.5 | Beta: 1 | Acc.: 58.81%

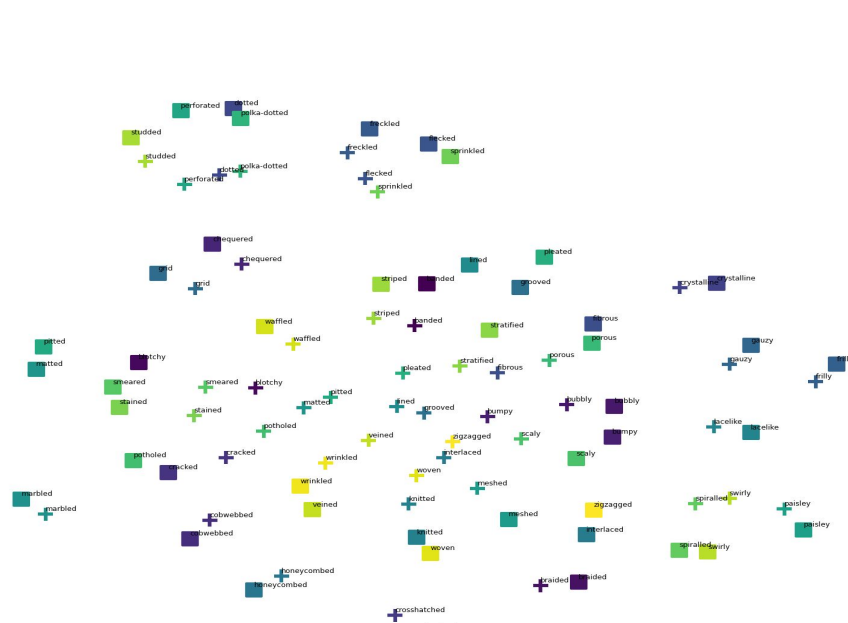


Image-Text Alignment  
Improvement

Alpha: 0.7 | Beta: 8 | Acc.: 68.79%



# Results (Model#2)

Dataset	Zero-shot						Fine-tune						
	CLIP	Proto-CLIP	Tip-A	Tip-A <sup>R</sup>	$\Delta^R \downarrow$	$\Delta \uparrow$	Proto-CLIP	Tip-A	Tip <sup>R</sup>	$\Delta^R \downarrow$	HP Searched	Tip <sup>R</sup>	$\Delta_F \uparrow$
Eurosat	37.56	<b>73.06</b>	70.54	70.57	0.03	2.49	81.46	84.54	84.52	0.02	<b>84.56</b>		<b>-3.10</b>
DTD	42.32	<b>61.58</b>	60.93	60.93	0.00	0.65	<b>68.79</b>	66.55	66.19	<u>0.36</u>	66.61		2.18
UCF101	61.38	<b>73.14</b>	70.58	70.66	0.08	2.48	<b>78.09</b>	78.03	77.16	<u>0.87</u>	77.50		0.59
SUN397	58.56	<b>68.07</b>	66.85	66.82	0.03	1.25	<b>71.96</b>	71.47	71.35	0.12	71.35		0.61
Stanford Cars	55.63	<b>67.95</b>	66.77	66.76	0.01	1.19	<b>75.24</b>	75.74	74.93	<u>0.81</u>	75.09		0.15
Oxford Pets	85.83	<b>88.80</b>	88.14	88.20	0.06	0.60	88.93	89.7	<b>89.62</b>	0.08	<b>89.62</b>		<b>-0.69</b>
Oxford Flowers	66.06	<b>92.90</b>	89.89	89.93	0.04	2.97	<b>95.17</b>	94.8	93.87	<u>0.93</u>	94.60		0.85
Food101	77.33	<b>78.00</b>	77.83	77.86	0.03	0.14	78.98	77.89	79.16	<u>1.27</u>	<b>79.39</b>		<b>-0.41</b>
FGVC	17.16	29.64	<b>29.82</b>	29.82	0.06	<b>-0.18</b>	34.83	35.55	34.56	<u>0.99</u>	<b>35.07</b>		<b>-0.24</b>
Caltech101	85.92	<b>91.00</b>	90.18	90.18	0.00	0.82	<b>93.59</b>	92.86	92.86	0.00	92.86		0.73
Imagenet	60.34	<b>62.73</b>	62.01	61.81	0.20	0.93	<b>65.49</b>	65.51	65.40	0.11	65.48		0.01

```
eurosat, 0.7, 10, 81.31, 81.46
dtd, 0.7, 8, 68.79, 68.74
UCF101, 0.7, 10, 78.09, 78.01
sun397, 0.7, 10, 71.96, 71.93
stanford_cars, 0.8, 10, 75.24, 75.21
oxford_pets, 0.4, 10, 88.93, 88.55
oxford_flowers 0.2, 10, 86.44, 95.17
food101, 0.1, 10, 78.40, 78.98
fgvc, 0.7, 20, 34.44, 34.83
caltech101, 0.9, 10, 93.59, 93.39
imagenet, 0.4, 13, 65.49, 65.28
```

**Different datasets have different  
alpha, beta requirements.**

Questions?